# VEHICLE DYNAMICS LIBRARY

Overview



#### **AGENDA**

- ☐ About Vehicle Dynamics Library
- ☐ Key Benefits
- ☐ Key Capabilities
- ☐ Key Applications
- ☐ Library Contents
- Modelon Compatibility
- ☐ Latest Release



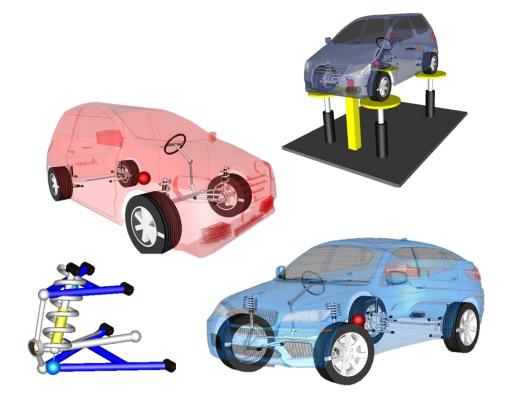




#### **ABOUT**

An environment for the design and analysis of vehicles and vehicular components

On the market since 2004



- - > f Information
  - > Examples
  - > Atmospheres
  - > 🗾 Drivers
  - > Grounds
  - > 📶 Scenes
  - > Vehicles
  - > iii Migration
  - > O RealTime
  - > 🗶 Utilities
    - World



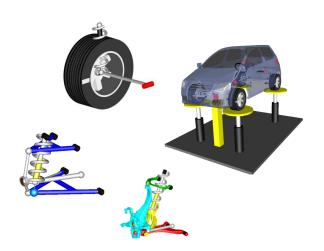


#### Open code

# model Spring "Linear 1D translational spring" extends Translational.Interfaces.PartialCompliant; parameter SI.TranslationalSpringConstant c(final min=0, start=1) "Spring constant"; parameter SI.Distance s\_rel0=0 "Unstretched spring length"; equation f = c\*(s\_rel - s\_rel0); a end Spring;

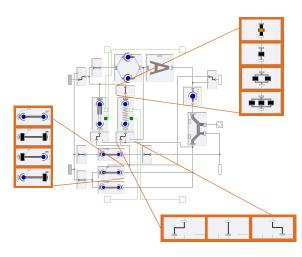
- View, extend and modify models to fit your needs
- Advantages similar to inhouse tool

#### Scalable



- Works at both system and component level
- Adapts to your workflows
- Easily switch between different levels of fidelity

#### Flexible

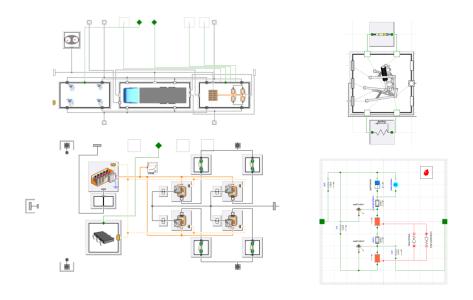


- No limit in configurability
- Design and evaluate innovative and non-traditional concepts





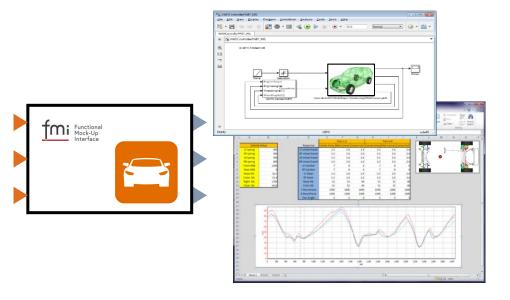
#### Multi-domain



- Model complete vehicle system
- Integrate electrical, hydraulic and pneumatic suspension components
- Electrified powertrains

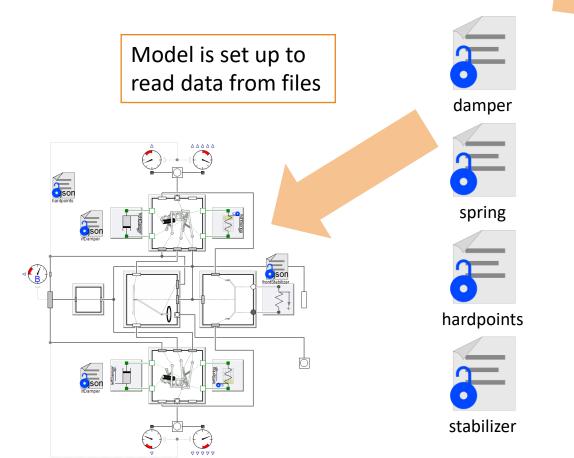


#### Deployable



- Spread models and analysis capability throughout organization
- Models usable in many environments (SIL, HIL, DIL, ...)
- Safely share models with suppliers

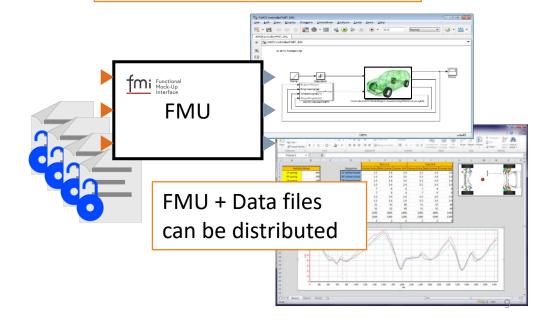
#### Parameterization





Link to data files is maintained in compiled model

Files can be changed to adjust parameterization





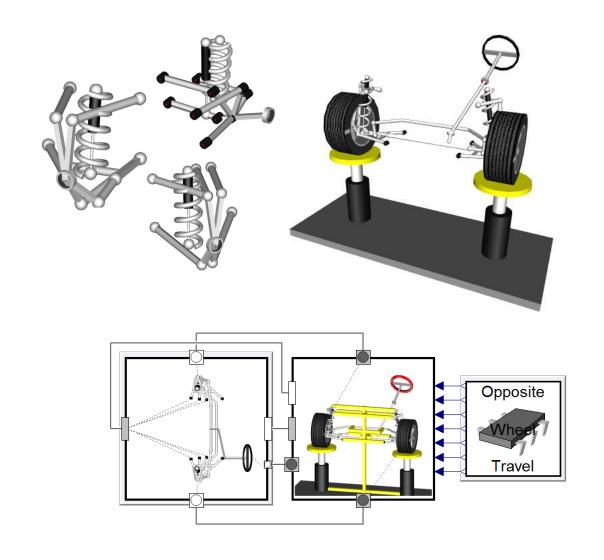


#### SUSPENSION DESIGN

Large set of predefined configurable topologies

Easily extend to custom topologies

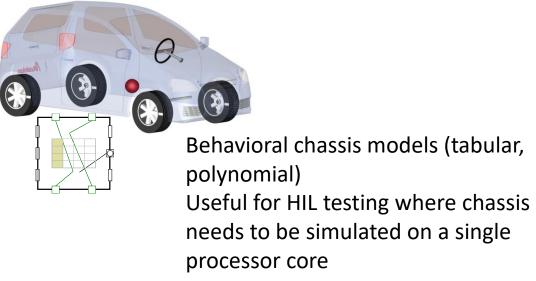
Different options for suspension rig tests





## REAL TIME SIMULATION

Use VDL models for driving simulators and HIL testing



Using parallel execution, also elasto-kinematic multibody models can be simulated in real time with multiple processor cores



Established workflows for several real-time environments



#### **CHASSIS TUNING**

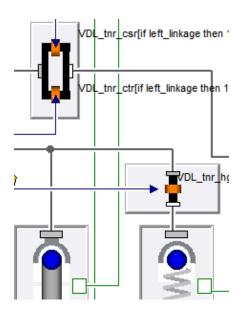
Components: tuners and tunables
OEMs

Automates ride height adjustment

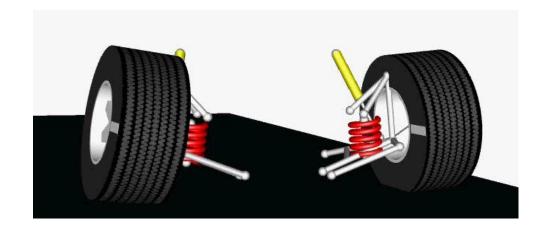
#### Motorsports

Replicate physical setup procedure such as shim adjustments, driver in/out, fuel, ballast...

Provide setup tools to aid in physical setup









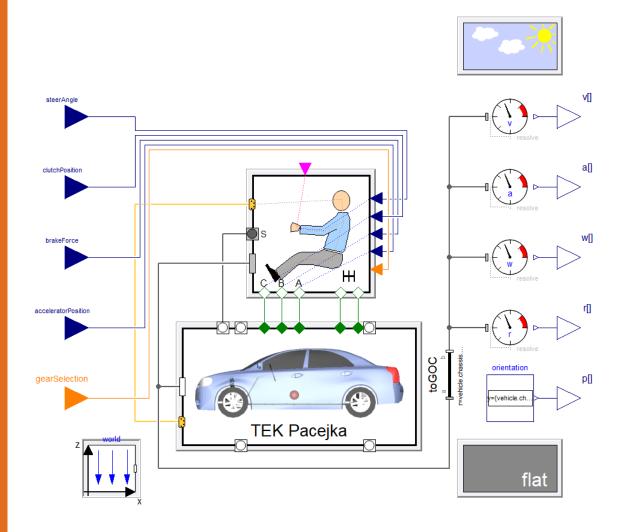
# PLANT MODELS FOR CONTROLS DEVELOPMENT

Export vehicle models for use in developing control systems

Scalable fidelity allows fast execution

Interface can be tailored to the specific application

Flexible deployment using FMI





#### **DRIVABILITY**

#### Challenge

To meet increasingly stringent fuel economy and emissions standards without compromising customers demands for vehicle performance



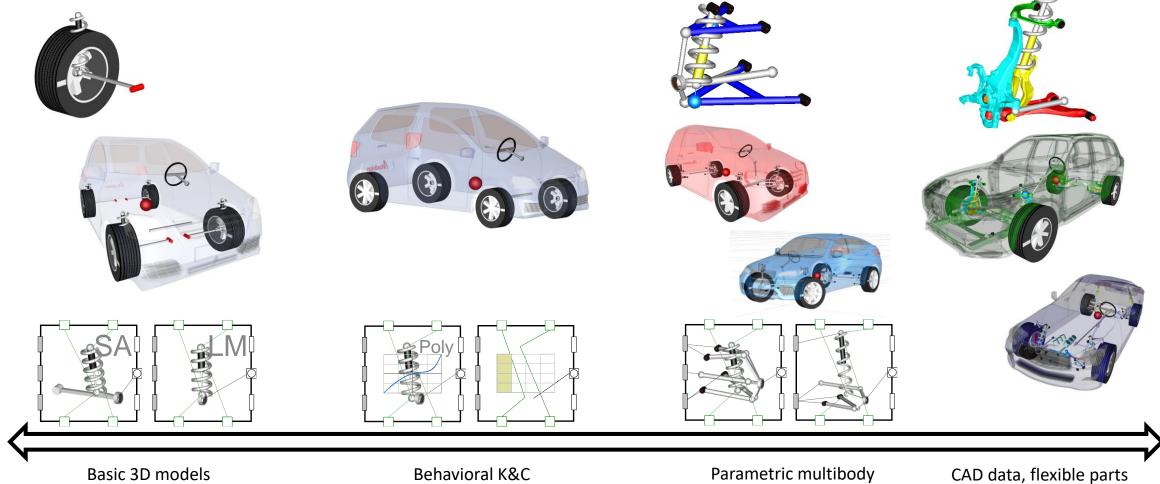
#### Issues

- Shift performance and feel due to increased number of vehicle shifts to optimize fuel economy
- Vehicle launch induced vibrations with both conventional and start-stop technology
- Driveline vibrations associated with dual clutch transmissions and driveline vibrations





#### **CHASSIS AND SUSPENSIONS**

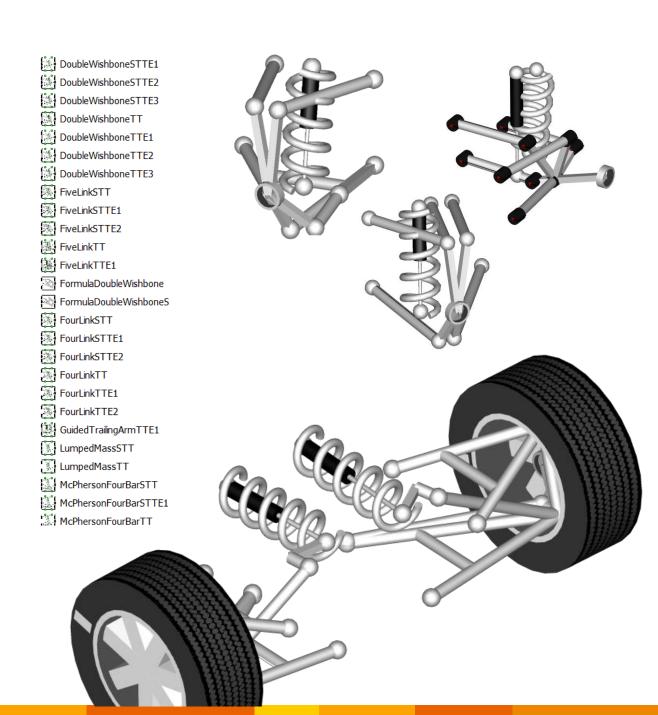




#### **SUSPENSIONS**

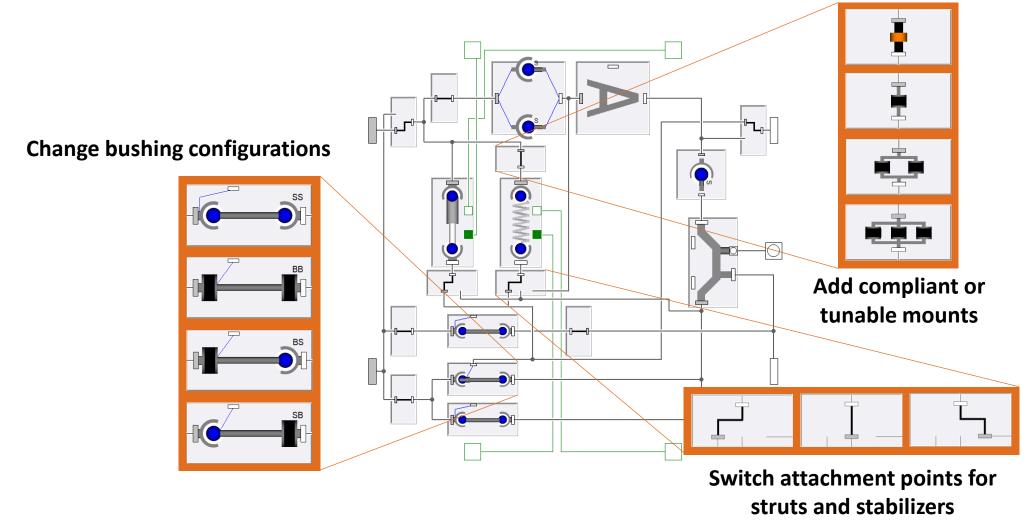
Contains all the Components necessary for detailed analysis of suspension and steering systems

- Extensive library of suspension components
  - Ride elements (springs/dampers/stabilizer bars)
  - Steering systems
- Over 30 different suspension topologies
  - Varying level of detail: planar, tabular, multibody
  - Kinematic and compliant (lumped/bushings)
  - Switchable attachments/mounts means 100s of configurations





#### **CONFIGURABLE TOPOLOGIES**

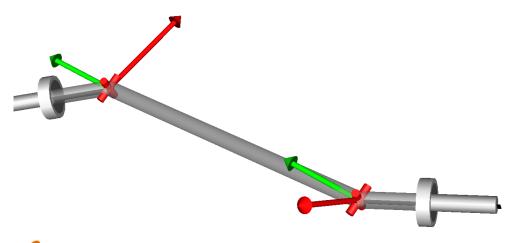


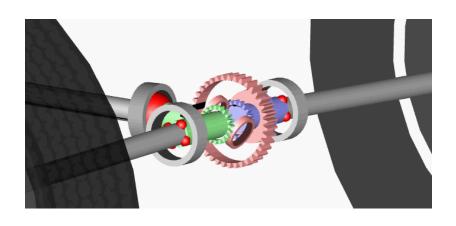


#### **POWERTRAIN - DRIVELINES**

Contains components and assembled subsystems to model various driveline implementations: front-, rear-, all-wheel drive

- Targeted to the development of vehicle drivelines
  - 3D effects in joints, shafts and gears
  - Geometry and kinematic effects
  - Reaction torques and forces
- Bridges the gap to very detailed subsystem models





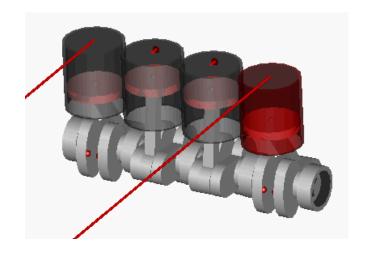


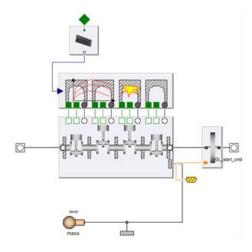
#### **POWERTRAIN - ENGINES**

- Pure torque map: torque as a function of throttle and engine speed
  - Applications: vehicle handling, drivability
- Pressure map (cycle resolved): cylinder pressure as a function of crank angle, throttle, engine control settings, and engine speed
  - Applications: engine, powertrain and driveline vibrations; and drivability

• More detailed (Engine Dynamics Library) engine models can be used to study gas exchange and

mean value torque production



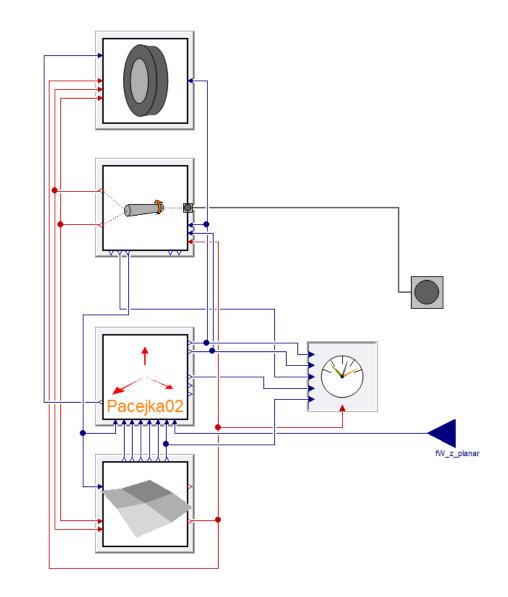




#### TIRES/ROADS

- Native tire models
  - Pacejka '94
  - Pacejka '02
  - Pacejka '12
  - Bakker '89
  - GSTBakker '87
  - Rill '05
  - Linear
- 3<sup>rd</sup> party interfaces
  - Delft Tire: MF-Tyre, MF-Swift
  - FTire
- User extensible
  - Modelica

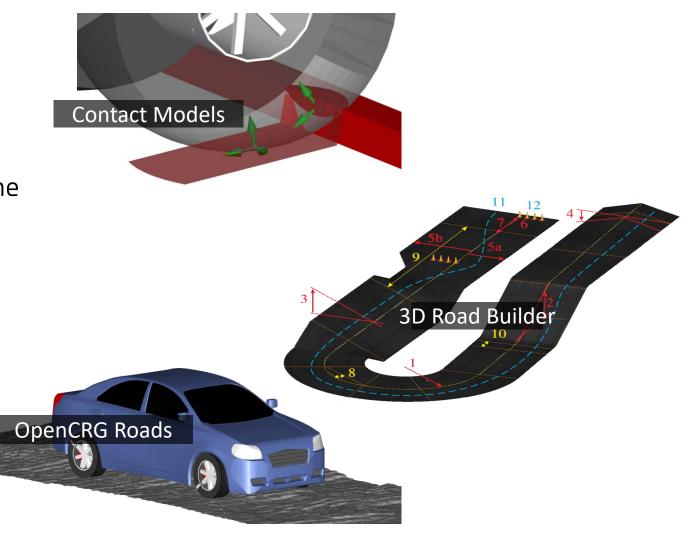




#### TIRES/ROADS

- Tire contact routines
  - Single point contact
  - Geometric/Enveloping
- 3D Road Builder
  - Closed loop/circuit from centerline
  - ISO3888-2 double lane change
  - NHTSA Fishhook
  - NHTSA J-turn
- Support for OpenCRG roads
- User extensible
  - Contact filtering
  - Ground lookup routines







#### RECOMMENDED MODELON LIBRARY COMPATIBILITY

- Vehicle Dynamic Library integrates with the Modelon Library Suite
  - Electrification Library
    - Electric drivelines, effects on vehicle dynamics
  - Hydraulics Library
    - Detailed hydraulic dampers
    - Hydraulic brake systems
  - Pneumatics Library
    - Air springs
    - Pneumatic brake systems





### **RELEASE: 2021.2**

#### **New Features**

#### **Electrified powertrains**

VDL is now dependent on the Electrification Library, which is now available to all VDL users starting with the 2021.2 release

There are two new electric vehicle examples, a Pickup with a quadmotor powertrain and a Coupe with either a dual-motor, or singlemotor powertrain

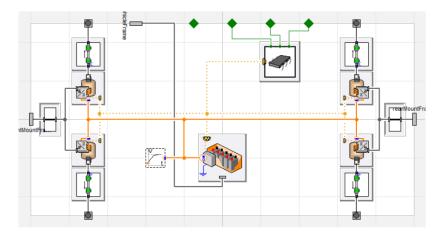
There is also a range of new electric powertrain examples, including Quad-, dual- and single motor configurations based on components from Electrification library

Finally, there are three example experiments, a **Range** estimation, **Acceleration** test and a **Torque Vectoring** test with the quad motor pickup vehicle.





New electric Pickup and Coupe vehicle examples



Quad motor powertrain example



### **RELEASE: 2021.2**

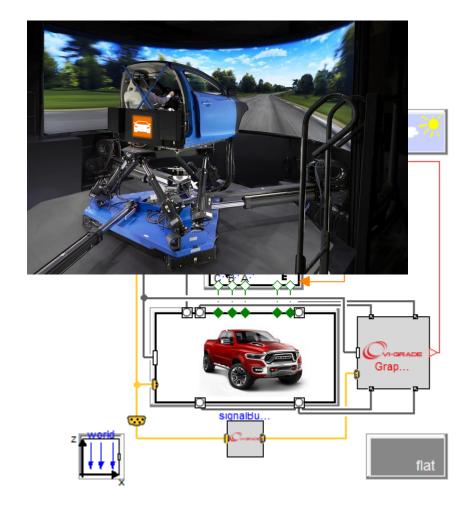
#### **New Features**

VDL models are now VI-Certified®

Vehicle models generated by VDL are now VI-Certified®.

VI-Certified is an elevated partner program aimed at validating 3rd party software operation on VI-grade® simulators. VI-grade develops and optimizes its Driving Simulators with a complete software suite for vehicle modeling, graphics, sound & vibration, and motion cueing, thus enabling an off-the-shelf, turn-key solution.

VI-Certified, that enables customers to use their established products, knowing that these products have been fully tested by partners and assured by VI-grade. This reduces cost and time of deployment for their Driving Simulators.





### **RELEASE: 2021.2**



### **Enhancements**

- Automatic transmission improvements, shift tables updated to improve shift logic in example transmissions
- New set of predefined drive cycles for DriveCycle driver
- · Additional templates for trucks and trailers
- Scale and offset parameters eliminated
- SimCenterTire updated to 2021.2
- Fixed bug in windup angle output of WheelAngles sensor
- FormulaSAE chassis updated to use newer suspension topologies and added to a new FormulaSAE vehicle model including brakes and powertrain

