



## **DYMOLA AND MODELICA**

#### Course overview

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#### Dymola and Modelica I

Introduction Dymola, Modelica, Modelon Overview of Dymola and Lecture 1 • Physical modeling Workshop 1 Workflow of modeling physical systems in Dymola Simulation and post-processing with Lecture 2 ٠ Dymola Workshop 2 Simulating and analyzing a physical system Configure system models Lecture 3 • Creating a reconfigurable system Workshop 3

#### Dymola and Modelica I

- Lecture 4
  - Workshop 4a
  - Workshop 4b
  - Workshop 4c
- Lecture 5
  - Workshop 5
- Lecture 6
  - Workshop 6

- Modelica I Writing Modelica models Cauer low pass filter using Electric Library
- A moving coil using Magnetic, Electric and Translational mechanics libraries
- c Temperature control using Heat transfer Library
  - Understanding equation-based modeling
  - Defining boundary conditions
    - Trouble shooting and common pitfalls Common pitfalls

#### Dymola and Modelica II

- Lecture 7
  - Workshop 7
- Lecture 8
  - Workshop 8a
  - Workshop 8b
- Lecture 9
  - Workshop 9a
  - Workshop 9b
  - Workshop 9c

Modelica II – Advanced features Implementing a solar collector Working with the Modelica Standard Library

- Lamp logic using StateGraph II Suspension linkage using MultiBody mechanics
  - Hybrid modeling
- Hybrid examples
  - Hammer impact model
- Designing a thermostat valve

#### Dymola and Modelica II

- Lecture 10
  - Workshop 10
- Lecture 11
  - Workshop 11
- Lecture 12
  - Workshop 12a
  - Workshop 12b FMI with Excel
  - Workshop 12c FMI with Simulink

Efficient and reconfigurable modeling

Creating a system architecture based on templates and interfaces

Model variants and data management

Creating a data architecture and adaptive parameter interfaces

FMI technology

Import and Export FMUs in Dymola

#### Dymola and Modelica II

- Lecture 13
- Workflow automation and scripting
- Workshop 13 Automated sensitivity analysis
- Lecture 14 •
  - Workshop 14a
  - Workshop 14b
  - Workshop 14c

- Dymola code with other tools
- Source code and binary export
- External functions and external objects
- Simulink export
  - Introduction to real-time Configuring a model for real-time simulation
- Lecture 15
  - Workshop 15

## Overview of Dymola and physical modeling



- Overview of Dymola
- Documentation
- Creating a new model
- Defining a model with several components
  - Connecting components, connectors
- Setting parameters, dialog boxes
- Interfacing:
  - Connector interface
  - Parameter interface
- Propagating parameters
- Organizing models in packages
- Using check in Dymola

## Simulation and post-processing



- What is an experiment?
- Setting up an experiment
- Working with results
- Analysis of results
- Exporting results
- Selecting solvers
- Initial conditions
- Understanding check, translate, simulate
- Understanding the translation and simulation logs

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## Configure system models



- Benefits with hierarchical models
- Structuring
- Configuring hierarchical models
  - Class vs component
  - Navigating
  - Setting and protecting parameters (encapsulation)
  - Changing components



### Modelica I - Writing Modelica models



- Dymola text editor
- Variables
  - Modifying attributes of variables
  - Units and physical quantities, unit checking
- Equations and Algorithms
  - Equations
  - Initial equations
  - Accessing information in connectors
  - Algorithms
- Arrays and matrices
- Inheritance
- Modelica Standard Library
- Multidomain modeling

#### Understanding equation-based modelling



- Equation-based components
  - Boundary conditions
  - Initialization
- Defining component boundaries
  - Potential and flow variables
  - Balanced models
  - Over-determined connectors
  - Input/output
  - Stream connectors
- Degrees of freedom in a system
  - State selection and index reduction
  - Identifying degrees of freedom in a system
- Other Modelica classes

## Troubleshooting and common pitfalls



- Development Best practice
  - Specification
  - Implementation
  - Maintenance
- Troubleshooting
  - Translation problems
  - Simulation problems
- Debugging
  - Nonlinear solver diagnostics
  - Min/Max assertion
  - Logging options (Events, State variables)
  - Online debugging
  - Translation and Advanced Dymola flags
- Common problems

#### Modelica II – Advanced Features



- Functions
  - Derivative, advanced derivative definitions
  - Inverse
  - Code generation annotations
- Enumerations
- Data records
- Component arrays
- Expandable connectors
  - Signal bus
- Synchronous Language elements

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#### Working with Modelica Standard Library



- StateGraph
  - Fundamentals and Usage
  - Modelica.StateGraph vs. Modelica\_StateGraph2
- Multibody Mechanics
  - Domain description and basic assumptions
  - Multi-body simulation in Dymola
- Fluid
  - Physical principles
  - Fundamentals and usage
- Media
  - Why and how is Media used?
  - Fundamentals

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## Hybrid modeling



- What is a hybrid system?
- What is an event?
- Chattering
- Avoiding events
- Variable structures
  - Parameterized curves
  - State machines



### Efficient and reconfigurable modeling



- Creating reconfigurable models
  - Templates and interfaces
  - Conditional components
  - Arrays of components
- Organizing models and data
  - Libraries
  - Data records



#### Model variants and data management



- Modifiers in specific models
- Data records
- Data input blocks
- Replaceable functions
- Reading data from files
- Package constants
- Working with deeper hierarchies



# LECTURE 12 FMI Technology



- Introduction and background
  - Why FMI?
- What is FMI?
  - The FMI standard
  - What is an FMU?
  - FMI Flavors
- Supported tools and testing
- FMI support in Dymola
  - Options
  - FMU import
  - FMU export
  - FMI workflow
- Using Dymola FMUs with other tools
  - Supported tools
  - Matlab/Simulink
  - Excel
  - Python



### Workflow automation and scripting



- Automated analysis
- Automatic script generation
- Scripts
- Scripting using functions
- Coupling commands to a model
- Example: Generating report data



# Using the Dymola code in other tools and environments



- Binary export
  - Running dymosim.exe
    - Stand alone
    - Compiled with the DDE or OPC options
    - Compiled as DLL with API to C
  - Source code export
- Interface for Java and Python
- External functions in Dymola
- External objects in Dymola
- Dymola-Simulink Interface

#### Introduction to Real-time



- Introduction
  - What is real-time simulation?
  - Why real-time?
  - Harder requirements
- Choosing solver
- Fast dynamics and instability
- Non-linear equation systems
- Analytical Jacobians

- Profiling
  - Execution time analysis
  - Code profiling
  - Overruns
  - Translation log
- Inline integration
- Mixed mode integration
- Achieving real-time simulation

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